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COSINE FAMILIES AND DAMPED SECOND ORDER DIFFERENTIAL EQUATIONS

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### **ABSTRACT**

Consider the abstract differential equation

(1) 
$$u''(t) + 2Bu'(t) = Au(t) + F(u(t)), t \in \mathbb{R}, u(0) = x,$$
  
 $u'(0) = y$ 

where A and B are densely defined linear operators and F is possibly nonlinear and unbounded. Assuming that  $A + B^2$  generates a cosine family C(t) and -B generates a group T(t), there is a variation of constants formula for (1); namely

(2) 
$$u(t) = T(t)[C(t)x + S(t)(Bx + y)$$

$$+ \int_0^t T(t-s)S(t-s)F(u(s)) ds,$$

where S(t) is the sine family associated with C(t). The motivating examples include  $w_{tt} + 2b(x)w_t = w_{xx} + f(w,w_x,w_t)$  and  $w_{tt} + 2w_{tx} = w_{xx} + f(w,w_x,w_t)$ , for  $0 < x < \pi$ ,  $t \in \mathbb{R}$ , w(x,0) = h(x),  $w_t(x,0) = g(x)$ , and various boundary conditions. We examine the existence of mild solutions and the asymptotic behavior when there is a damping effect introduced by the 2Bu'(t) term.

AMS(MOS) Subject Classification: 34G20, 35L15

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## SIGNIFICANCE AND EXPLANATION

A variation of constants formula is given for certain second order differential equations in a Banach space. The abstract results obtained can be applied to a class of damped semilinear hyperbolic partial differential equations; in particular, the existence and asymptotic behavior of solutions of such equations is examined.

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# COSINE FAMILIES AND DAMPED SECOND ORDER DIFFERENTIAL EQUATIONS

## James H. Lightbourne, III Samuel M. Rankin, III

1. INTRODUCTION. Let X be a Banach space and A and B be linear operators on X with domains D(A) and D(B) respectively. F will denote a nonlinear, possibly unbounded map on X. We consider the abstract differential equation:

(1.1) 
$$u''(t) + 2Bu'(t) = Au(t) + F(u(t)), t \in \mathbb{R}$$
  
 $u(0) = x, u'(0) = y$ 

Essentially under the assumption that  $A + B^2$  generates a cosine family C(t),  $t \in R$ , of linear operators on X and that -B generates a group T(t), we will establish existence for (1.1) and examine the asymptotic behavior of (1.1) when there is a damping effect introduced by the term 2Bu'(t). We will actually consider "mild" solutions of (1.1); i.e., solutions of the variation of constants equation:

(1.2) 
$$u(t) = T(t)[C(t)x + S(t)(Bx + y)] + \int_0^t T(t - s)S(t - s)F(u(s))ds,$$

where S(t) is the sine family associated with C(t).

Two situations to which the abstract theory applies are indicated by the following examples.

(1.3) 
$$w_{tt}(x,t) + 2b(x)w_{t}(x,t) = w_{xx}(x,t) + f(w(x,t), w_{x}(x,t)),$$

$$t \in \mathbb{R}, \quad 0 < x < \pi$$

$$w(x,0) = h(x), \quad w_{t}(x,0) = g(x), \quad 0 \le x \le \pi$$

$$w(0,t) = w(\pi,t) = 0, \quad t \in \mathbb{R}$$

where b:  $[0,\pi] \rightarrow \mathbb{R}$  is continuous. Asymptotic behavior for (1.3)

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and  $f \equiv 0$  has been considered by Rauch [3]. The second illustrative example is

(1.4) 
$$w_{tt}(x,t) + 2w_{xt}(x,t) = w_{xx}(x,t) + f(w(x,t), w_{x}(x,t)),$$

$$t \in \mathbb{R}, \quad 0 < x < \pi$$

$$w(x,0) = h(x), \quad w_{t}(x,0) = g(x), \qquad 0 \le x \le \pi$$

$$w(0,t) = w(\pi,t), \quad w_{x}(0,t) = w_{x}(\pi,t), \quad t \in \mathbb{R}$$

The preliminaries in section 2 include the known properties of cosine families that we will use and the assumptions on A and B which will be made throughout the paper. Also, in section 2 we establish the relationship between equations (1.1) and (1.2). In section 3 we give existence criteria for equation (1.2) and some global properties of solutions are given in section 4. The examples are discussed in section 5.

2. PRELIMINARIES. Let X be a Banach space with norm | • |.

DEFINITION. A one-parameter family  $\{C(t): t \in \mathbb{R}\}$  of bounded linear operators on X is called a strongly continuous cosine family provided

- (i) C(0) = I, the identity on X;
- (ii) C(s + t) + C(s t) = 2C(s)C(t), for all  $s,t \in \mathbb{R}$ ; and
- (iii) for each  $x \in X$ ,  $C(\cdot)x: \mathbb{R} \to X$  is continuous.

Associated with C(t) is the sine family  $\{S(t): t \in \mathbb{R}\}$  defined by  $S(t)x = \int_0^t C(s)x \, ds$  for  $x \in X$ , the infinitesimal generator of C(t) is the linear operator  $G: D(G) \to X$  defined by Gx = C''(0)x where

 $D(G) = \{x \in X: C(\cdot)x: \mathbb{R} \to X \text{ is twice continuously} differentiable}\}.$ 

We also refer to the set E defined by

 $E = \{x \in X: C(\cdot)x: \mathbb{R} \to X \text{ is continuously differentiable}\}.$ 

The proof of the following proposition as well as a more complete discussion of cosine families may be found in Travis and Webb [4].

PROPOSITION 2.1. Let  $\{C(t): t \in \mathbb{R}\}$  be a strongly continuous cosine family of bounded linear operators on X with generator G. The following properties hold:

- (i) G is a closed operator on X with domain D(G) dense in X;
- (ii) if  $x \in X$ , then  $S(t)x \in E$  and S'(t)x = C(t)x;
- (iii) if  $x \in E$ , then  $S(t)x \in D(G)$  and S''(t)x = GS(t)x;
- (iv) if  $x \in E$ , then C'(t)x = GS(t)x;
- (v) if  $x \in D(G)$ , then  $S(t)x \in D(G)$  and GS(t)x = S(t)Gx;
- (vi) if  $x \in D(G)$ , then  $C(t)x \in D(G)$  and C''(t)x = GC(t)x = C(t)Gx;
- (vii) C(t + s) C(t s) = 2GS(t)S(s), for all  $s, t \in \mathbb{R}$ ;
- (viii) S(s + t) = S(s)C(t) + S(t)C(s), for all  $s,t \in \mathbb{R}$ ;
  - (ix) C(t), S(s), C(s), S(t) commute for  $s,t \in \mathbb{R}$ ;
  - (x) there exist constants  $K \ge 1$  and  $\omega \ge 0$  such that  $|C(t)| \le Ke^{\omega|t|} \text{ and } |S(t) S(\hat{t})| \le K|f_{\hat{t}}^{\hat{t}} e^{\omega|s|} ds| \text{ for all } t, \hat{t} \in \mathbb{R}.$

Throughout this paper we will make the following suppositions on A and B. Recall that  $\{T(t): t \in \mathbb{R}\}$  is said to be a strongly continuous

- (2.1) A and B are densely defined linear operators on X with domains  $D(A) \subset D(B)$ .
- (2.2)  $G = A + B^2$  generates a strongly continuous cosine family  $\{C(t): t \in \mathbb{R}\}.$
- (2.3) -B generates a strongly continuous group  $\{T(t): t \in \mathbb{R}\}$  of linear operators on X.

We will also refer to the regularity conditions:

- (2.4)  $D(G) = D(A + B^2) \leq D(A)$ .
- (2.5) T(t): D(A) + D(A).
- (2.6)  $E \subseteq D(B)$  and if  $\{S(t): t \in \mathbb{R}\}$  is the sine family associated with C(t), then  $t \to BS(t)x$  is continuous for each  $x \in X$  and if  $x \in D(B)$  then S(t)Bx = BS(t)x.
- (2.7) If  $x \in D(B)$ , then  $C(t)x \in D(B)$  and C(t)Bx = BC(t)x.
- (2.8) For  $x \in X$ ,  $\int_{\mathbf{r}}^{S} T(u)S(u)x du \in D(A)$  and

$$A \int_{\mathbf{r}}^{S} T(u)S(u)x \ du = T(s)C(s)x - T(\mathbf{r})C(\mathbf{r})x$$

$$+ BT(s)S(s)x - BT(\mathbf{r})S(\mathbf{r})x.$$

The authors do not know if (2.8) is a consequence of (2.1) - (2.7); however, it is observed in section 5 that the examples satisfy (2.1) - (2.8).

PROPOSITION 2.2 (Travis and Webb [5]). Suppose P is a closed linear operator on X such that

- (i)  $S(t) \in D(P)$  for all  $t \in \mathbb{R}$  and  $x \in X$ ; and
- (ii) for each  $x \in X$ , the map  $t \to PS(t)x$  is continuous.

Then there exists  $M \ge 1$  and  $\omega^* \ge \omega$  such that  $|PS(t)| \le Me^{\omega^*|t|}$  for all  $t \in \mathbb{R}$ , where  $\omega$  is given in Proposition 2.1(x).

REMARK. Assuming condition (2.6), there exists  $M \ge 1$  and  $\omega^* \ge \omega$  such that  $|BS(t)| \le Me^{\omega^*|t|}$ .

The following proposition justifies referring to a solution of equation (1.2) as a mild solution of (1.1).

PROPOSITION 2.3. Suppose (2.1) - (2.8) hold and  $g: \mathbb{R} \to X$  is continuous. If  $g: \mathbb{R} \to X$  is continuously differentiable,  $x \in D(G)$  with  $Bx \in E$ ,  $y \in E$ , and u satisfies

(2.9) 
$$u(t) = T(t)[C(t)x + S(t)(Bx + y)] + \int_0^t T(t-s)S(t-s)g(s) ds,$$

then  $u(t) \in D(A)$ ,  $u'(t) \in D(B)$  for all  $t \in \mathbb{R}$ , u is twice continuously differentiable, and u satisfies

(2.10) 
$$u''(t) + 2Bu'(t) = Au(t) + g(t)$$
$$u(0) = x, \quad u'(0) = y.$$

Conversely, if u is twice continuously differentiable,  $u(t) \in D(A)$  and  $u'(t) \in D(B)$  for  $t \in \mathbb{R}$ , and u satisfies (2.10), then u satisfies (2.9).

**Proof.** To show that a solution of equation (2.9) satisfies (2.10), we first define

$$v(t) = \int_0^t T(t - s)S(t - s)g(s) ds.$$

Then

$$v(t) = \int_0^t T(t-s)S(t-s)g(0) ds + \int_0^t \int_u^t T(t-s)S(t-s)g'(u) ds du$$

$$= \int_0^t T(t-s)S(t-s)g(0) ds + \int_0^t \int_0^{t-u} T(s)S(s)g'(u) ds du$$

Using condition (2.8), we have  $v(t) \in D(A)$  and

Also,

$$v'(t) = T(t)S(t)g(0) + \int_0^t T(s)S(s)g'(t-s) ds$$

$$= T(t)S(t)g(0) + \int_0^t T(t-s)S(t-s)g'(s) ds$$

and

$$v''(t) = T(t)C(t)g(0) - BT(t)S(t)g(0)$$

$$+ \int_{0}^{t} [BT(t-s)S(t-s)g'(s) + T(t-s)C(t-s)g'(s)] ds$$

$$= Av(t) + g(t)$$

Defining  $V_H(t) = T(t)[C(t)x + S(t)(Bx + y)]$  and using a straightforward computation, one can establish that

$$v_{H}''(t) + 2Bv_{H}'(t) = Av_{H}(t).$$

Noting that  $u(t) = v_H(t) + v(t)$ , it follows that u satisfies (2.10). To establish the converse statement, observe that

$$\frac{d}{ds} T(t - s)S(t - s)u'(s) = T(t - s)[-C(t - s)u (s) + S(t - s)u'(s)]$$

$$+ BT(t - s)S(t - s)u'(s)$$

$$= -T(t - s)C(t - s)u'(s)$$

$$+ T(t - s)S(t - s)[Au(s) - 2Bu'(s) + g(s)]$$

$$+ BT(t - s)S(t - s)u'(s)$$

and

$$\frac{d}{ds} T(t-s)C(t-s)u(s) = T(t-s)[-(A + B^2)S(t-s)u(s) + C(t-s)u'(s)] + BT(t-s)C(t-s)u(s)$$

Integrating we obtain

$$-T(t)S(t)u (0) = \int_{0}^{t} [-T(t-s)C(t-s)u'(s) + T(t-s)S(t-s)Au(s) - T(t-s)S(t-s)Bu'(s) + T(t-s)S(t-s)g(s)] ds$$

and

$$u(t) - T(t)C(t)u(0) = \int_0^t [-T(t-s)AS(t-s)u(s) - T(t-s)B^2S(t-s)u(s) + T(t-s)C(t-s)u'(s) + BT(t-s)C(t-s)u(s)] ds$$

Addition of the two formulas yields

$$u(t) - T(t)S(t)u'(0) - T(t)C(t)u(0)$$

$$= \int_{0}^{t} T(t-s)S(t-s)g(s) ds$$

$$+ \int_{0}^{t} [BT(t-s)C(t-s)u(s) - T(t-s)S(t-s)Bu'(s)$$

$$- T(t-s)B^{2}S(t-s)u(s)] ds$$

$$= \int_{0}^{t} T(t-s)S(t-s)g(s) ds - \int_{0}^{t} \frac{d}{ds} [T(t-s)S(t-s)Bu(s)] ds$$

$$= \int_{0}^{t} T(t-s)S(t-s)g(s) ds + T(t)S(t)Bu(0)$$

and it is seen that u satisfies (2.9).

3. EXISTENCE. In this section we establish the existence of solutions to equation (1.2) under various assumptions on the cosine family C(t) generated by  $G = A + B^2$  and the nonlinear function F.

PROPOSITION 3.1 (Fattorini [1]). If G is the generator of a strongly continuous cosine family then there exists a translation  $G_c \equiv G - c^2 I$  of G such that

- (i)  $G_c^{-1}$  exists as a bounded operator on X and
- (ii) for  $0 \le \alpha \le 1$  the fractional powers  $(-G_c)^{\alpha}$  exist as closed, densely defined operators with  $D(G) \subset D((-G_c)^{\alpha_1}) \subset D((-G_c)^{\alpha_2}) \quad \text{for } 0 \le \alpha_2 \le \alpha_1 \le 1.$

The existence of  $(-G_c)^{-1}$  implies that  $(-G_c)^{-\alpha}$  exists as a bounded linear operator on X and consequently  $D((-G_c)^{\alpha})$  becomes a Banach space  $X_{\alpha}$  with norm  $|x|_{\alpha} = |(-G_c)^{\alpha}x|$ . Also in [1], it was shown that if  $X = \mathcal{L}^p$ ,

 $1 then <math>E \subset D((-G_c)^{1/2})$  and for each  $x \in X$ ,  $(-G_c)^{1/2}S(\cdot)x: \mathbb{R} \to X$  is continuous. For general Banach space X, Rankin [2] showed that  $E \subset D((-G_c)^{\alpha})$  for all  $0 \le \alpha < 1/2$ . We shall make the following assumptions:

- (3.1) There exists  $0 < \lambda < 1$  such that  $E \subset D((-G_c)^{\lambda})$  and  $(-G_c)^{\lambda}S(\cdot)x \colon \mathbb{R} \to X$  is continuous for  $x \in X$ .
- (3.2) If  $0 \le \alpha \le 1$  and  $x \in \mathbb{D}((-G_c)^{\alpha})$ , then  $T(t)x \in \mathbb{D}((-G_c)^{\alpha})$  with  $(-G_c)^{\alpha}T(t)x = T(t)(-G_c)^{\alpha}x$  for all  $t \in \mathbb{R}$ .

REMARK. If condition (3.1) holds, then by Proposition 2.2 there exists  $M_{\lambda} \geq 1$  and  $\omega_{\lambda} \geq \omega$  such that  $\left| \left( -G_{c} \right)^{\lambda} S(t) \right| \leq M_{\lambda} e^{\omega_{\lambda} |t|}$  for all  $t \in \mathbb{R}$ .

THEOREM 3.1. In addition to (2.1) - (2.3), (3.1), and (3.2), suppose  $D \subset X_{\lambda} \text{ is open. If } F:D \to X \text{ satisfies } |F(x_1) - F(x_2)| \leq L|x_1 - x_2|_{\lambda} \text{ for some } L > 0 \text{ and all } x_1, x_2 \in D, \text{ then for each } x \in D \cap D(B) \text{ and } y \in X$  there exists a > 0 and a unique continuous function  $u: [-a,a] \to X_{\lambda}$  such that u satisfies (1.2).

Proof. The proof employs the contraction mapping principle. Choose  $\delta > 0$  and N > 0 such that if

$$W(x,\delta) = \{z \in X : |z - x|_{\lambda} < \delta\}$$

then  $W(x,\delta) \subset D$  and  $|F(z)| \le N$  for  $z \in W(x,\delta)$ . Choose a > 0 such that for  $t \in [-a,a]$ 

$$\begin{split} & \left| T(t)C(t)x - x \right|_{\lambda} + \left| T(t)S(t)(Bx + y) \right|_{\lambda} \le \frac{\delta}{2} \ , \\ & N \! \int_{-a}^{a} \left| T(s)(-G_c)^{\lambda}S(s) \right| \ ds < \frac{\delta}{2} \ , \quad \text{and} \\ & L \! \int_{-a}^{a} \left| T(s)(-G_c)^{\lambda}S(s) \right| \ ds < 1 . \end{split}$$

Define

$$K = \{v \in \{([-a,a]; X_{\lambda}): \sup_{-a \le t \le a} |v(t) - x|_{\lambda} \le \delta\}$$

and the map H:  $K + ([-a,a]; X_{\lambda})$  by

$$[Hv](t) = T(t)[C(t)x + S(t)(Bx + y)] + \int_0^t T(t-s)S(t-s)F(v(s)) ds$$

The choice of  $\delta$  and a implies that H: K  $\Rightarrow$  K. Furthermore, for  $v_1, v_2 \in K$ 

$$\begin{aligned} \left| \text{Hv}_{1}(t) - \text{Hv}_{2}(t) \right|_{\lambda} & \leq \int_{0}^{t} \left| \text{T}(t-s) \left( -G_{c} \right)^{\lambda} \text{S}(t-s) \left[ \text{F}(v_{1}(s)) - \text{F}(v_{2}(s)) \right] \right| \, ds \\ \\ & \leq L \int_{0}^{t} \left| \text{T}(t-s) \left( -G_{c} \right)^{\lambda} \text{S}(t-s) \right| \, \left| v_{1}(s) - v_{2}(s) \right|_{\lambda} \, ds \end{aligned}$$

and by the choice of a we have that H satisfies the hypothesis of the contraction mapping principle. The assertions follow.

THEOREM 3.2. In addition to assumptions (2.1) - (2.5), (3.1), and (3.2), suppose  $(-G_C)^{-1}$  is compact. Let  $D \in X_{\lambda}$  be open and  $0 < \beta$ . If  $F:D \to X_{\beta}$  is continuous, then for each  $x \in D \cap D(B)$  and  $y \in X$  there exist a > 0 and a continuous function  $u: [-a,a] \to X_{\lambda}$  satisfying (1.2).

**Proof.** Let  $\delta > 0$  and N > 0 be such that if

$$W(x,\delta) = \{z \in X : |z - x|_{\lambda} < \delta\}$$

then  $W(x,\delta) \subset D$  and  $|F(z)|_{\beta} \leq N$  for  $z \in w(x,\delta)$ . Choose a > 0 such that

$$|T(t)C(t)x - x|_{\lambda} + |T(t)S(t)(Bx + y)|_{\lambda} \le \frac{\delta}{2}$$

and

$$N\int_{-2}^{a} |T(s)(-G_c)^{\lambda}S(s)| ds < \frac{\delta}{2}.$$

Define the set K and map H as in the proof of Theorem 3.1. As in Theorem 3.1, the choice of  $\delta$  and a implies that H: K  $\rightarrow$  K. For  $v_1, v_2 \in K$ ,

$$|Hv_1(t) - Hv_2(t)|_{\lambda} \le \int_0^t |T(t-s)(-G_c)^{\lambda}S(t-s)| |F(v_1(s)) - F(v_2(s))| ds$$

and the continuity of H follows from the continuity of F: D  $\rightarrow$  X<sub>B</sub>. To show that {Hv:  $v \in K$ } is an equicontinuous family in  $([-a,a]; Y_{\lambda})$ , we observe that if  $(G_c)^{-1}$  is compact then  $(-G_c)^{-\alpha}$  is compact for  $0 < \alpha < 1$  (see Travis and Webb [6]). For  $-a \le t_1 < t_2 \le a$  and  $v \in K$ 

$$|Hv(t_1) - Hv(t_2)|_{\lambda}$$

$$\leq |T(t_{2})C(t_{2})x - T(t_{1})C(t_{1})x|_{\lambda} + |T(t_{2})S(t_{2})(Bx + y) - T(t_{1})S(t_{1})(Bx + y)|_{\lambda}$$

$$+ \int_{t_{1}}^{t_{2}} |T(t_{2} - s)S(t_{2} - s)F(v(s))|_{\lambda} ds$$

+ 
$$\int_0^{\tau_2} |[T(t_2 - s)S(t_2 - s) - T(t_1 - s)S(t_1 - s)]F(v(s))|_{\lambda} ds.$$

Now write

$$\begin{split} &\int_{0}^{t_{1}} \left| \left[ T(t_{2} - s)S(t_{2} - s) - T(t_{1} - s)S(t_{1} - s) \right] F(v(s)) \right|_{\lambda} ds \\ &\leq &\int_{0}^{t_{1}} \left| T(t_{2} - s) \left[ (-G_{c})^{\lambda} S(t_{2} - s) - (-G_{c})^{\lambda} S(t_{1} - s) \right] (-G_{c})^{-\beta} (-G_{c})^{\beta} F(v(s)) \right| ds \\ &+ &\int_{0}^{t_{1}} \left| T(t_{2} - s) \left[ T(t_{2} - t_{1}) - I \right] (-G_{c})^{-\beta} (G_{c})^{\lambda} S(t_{1} - s) (-G_{c})^{\beta} F(v(s)) \right| ds \end{split}.$$

The equicontinuity of the family  $\{Hv: v \in K\}$  follows since

$$\{(-G_c)^{-\beta}(-G_c)^{\beta}F(y): y \in W(x,\delta)\}$$

and

$$\{(-G_c)^{-\beta}(G_c)^{\lambda}S(t_1-s)(-G_c)^{\beta}F(y): y \in W(x,\delta), 0 \le s \le t_1 \le a\}$$

are precompact sets in X and the maps  $t o (-G_c)^{\lambda} S(t)$  and t o T(t) are continuous uniformly on compact sets of X. Also, for each  $v \in K$  and  $t \in [-a,a]$ 

$$(-G_c)^{\lambda} Hv(t) = T(t)C(t)(-G_c)^{\lambda}x + T(t)(-G_c)^{\lambda}S(t)(Bx + y)$$

$$+ \int_0^t T(t-s)(-G_c)^{-\beta}(-G_c)^{\lambda}S(t-s)(-G_c)^{\beta}F(v(s)) ds$$

and consequently,  $\{Hv(t): v \in K \text{ and } t \in [-a,a]\}$  is precompact in  $X_{\lambda}$ . Thus by the Ascoli-Arzela Theorem  $\{Hv: v \in K\}$  is precompact in  $X_{\lambda}$  and the assertions of the theorem follow from the Schauder Fixed Point Theorem.

THEOREM 3.3. In addition to assumptions (2.1) - (2.5), (3.1), and (3.2), suppose  $(-G_c)^{-1}$  is compact and  $0 \le \beta < \lambda$ . If  $D \in X_\beta$  is open and  $F:D \to X$  is continuous, then for each  $x \in D \cap D(B)$  and  $y \in X$  there exist a > 0 and a continuous function  $u: [-a,a] \to X_\beta$  satisfying (1.2).

Proof. The proof is similar to that of the previous theorem. Let  $\delta>0\,$  and  $\,N>0\,$  be such that if

$$W(x,\delta) = \{z \in X : |z - x|_{\beta} < \delta\}$$

then  $W(x,\delta) \subset D$  and  $|F(z)| \leq N$  for  $z \in W(x,\delta)$ . Define K and H as before. One shows H: K  $\rightarrow$  K and is continuous. Writing

$$(-G_{c})^{\beta}Hv(t) = T(t)C(t)(-G_{c})^{\beta}x + T(t)(-G_{c})^{\beta}S(t)(Bx + y)$$

$$+ \int_{0}^{t} T(t - s)(-G_{c})^{\beta - \lambda}(-G_{c})^{\lambda}S(t - s)F(v(s)) ds$$

one observes that { Hv(t):  $v \in K$  and t  $\epsilon$  [-a,a]} is precompact in  $X_{\beta}$  and writing

$$\begin{aligned} & \left| \mathsf{Hv}(\mathsf{t}_2) - \mathsf{Hv}(\mathsf{t}_1) \right|_{\beta} \\ & \leq \left| \mathsf{T}(\mathsf{t}_2) \mathsf{C}(\mathsf{t}_2) \mathsf{x} - \mathsf{T}(\mathsf{t}_1) \mathsf{C}(\mathsf{t}_1) \mathsf{x} \right|_{\beta} + \left| \mathsf{T}(\mathsf{t}_2) \mathsf{S}(\mathsf{t}_2) (\mathsf{Bx} + \mathsf{y}) - \mathsf{T}(\mathsf{t}_1) \mathsf{S}(\mathsf{t}_1) (\mathsf{Bx} + \mathsf{y}) \right|_{\beta} \\ & + \int_{\mathsf{t}_1}^{\mathsf{t}_2} \left| \mathsf{T}(\mathsf{t}_2 - \mathsf{s}) \mathsf{S}(\mathsf{t}_2 - \mathsf{s}) \mathsf{F}(\mathsf{v}(\mathsf{s})) \right|_{\beta} \, d\mathsf{s} \\ & + \int_{\mathsf{0}}^{\mathsf{t}_1} \left| \mathsf{T}(\mathsf{t}_2 - \mathsf{s}) \left[ (-\mathsf{G}_\mathsf{c})^\lambda \mathsf{S}(\mathsf{t}_2 - \mathsf{s}) - (-\mathsf{G}_\mathsf{c})^\lambda \mathsf{S}(\mathsf{t}_1 - \mathsf{s}) \right] (-\mathsf{G}_\mathsf{c})^{\beta - \lambda} \mathsf{F}(\mathsf{v}(\mathsf{s})) \right| \, d\mathsf{s} \\ & + \int_{\mathsf{0}}^{\mathsf{t}_1} \left| \mathsf{T}(\mathsf{t}_2 - \mathsf{s}) \left[ \mathsf{T}(\mathsf{t}_2 - \mathsf{t}_1) - \mathsf{I} \right] (-\mathsf{G}_\mathsf{c})^{\beta - \lambda} (\mathsf{G}_\mathsf{c})^\lambda \mathsf{S}(\mathsf{t}_1 - \mathsf{s}) \mathsf{F}(\mathsf{v}(\mathsf{s})) \right| \, d\mathsf{s} \end{aligned}$$

one observes that the family  $\{Hv: v \in K\}$  is equicontinuous. Consequently,  $H(K) \subset X$  is precompact the the assertions follow.

REMARK. In addition to the hypothesis of Theorem 3.1, 3.2, or 3.3, suppose the regularity conditions (2.6) and (2.7) hold. Then if  $x \in E$  and  $y \in X$ , we have that u' exists and u': [-a,a]  $\rightarrow X$  is continuous. If the regularity conditions (2.4) - (2.8) hold, F is continuously Frechet differentiable,  $x \in D(G)$  with  $Bx \in E$ , and  $y \in E$ , then u satisfies (1.1).

The final theorem of this section gives sufficient criteria for global existence.

### THEOREM 3.4. Assume that either

- (i) the suppositions of Theorem 3.1 hold, or
- (ii) the suppositions of Theorem 3.2 (3.3) hold and F maps bounded sets of D into bounded sets of  $X_R$  (X).

and the regularity conditions (2.6) - (2.7) hold. If  $x \in E$  and  $y \in X$  and u is a solution of equation (1.2) noncontinuable to the right on [0,d], then either  $d = +\infty$  or, given any closed bounded set  $V \subset D$ , there exists a sequence  $t_k + d^-$  such that  $u(t_k) \notin V$ . An analogous result holds for noncontinuability to the left.

Proof. The proofs under assumptions (i) and (ii) are similar; only assumption (ii) with Theorem 3.2 is considered. For contradiction, suppose  $d < \infty$  and there exists a bounded closed set  $V \subset D$  such that  $u(t) \in V$  for all  $t \in [0,d)$ . For  $0 \le t_1 < t_2 < d$  and u satisfying equation (1.2), we have

$$\begin{aligned} \left| u(t_{2}) - u(t_{1}) \right|_{\lambda} &\leq \left| T(t_{2})C(t_{2}) \left( -G_{c} \right)^{\lambda} x - T(t_{1})C(t_{1}) \left( -G_{c} \right)^{\lambda} x \right| \\ &+ \left| \left[ T(t_{2}) \left( -G_{c} \right)^{\lambda} S(t_{2}) - T(t_{1}) \left( -G_{c} \right)^{\lambda} S(t_{1}) \right] \left( Bx + y \right) \right| \\ &+ \int_{t_{1}}^{t_{2}} \left| T(t_{2} - s) \left( -G_{c} \right)^{\lambda} S(t_{2} - s) F(u(s)) \right| ds \\ &+ \int_{0}^{t_{1}} \left| \left[ T(t_{2} - s) \left( -G_{c} \right)^{\lambda} S(t_{2} - s) - T(t_{1} - s) \left( -G_{c} \right)^{\lambda} S(t_{1} - s) \right] F(u(s)) \right| ds. \end{aligned}$$

Noting that  $\{F(u(s)): 0 \le s < d\} \subset F(V)$  is bounded in  $X_{\beta}$  and thus precompact in X and that  $t \to T(t)(-G_c)^{\lambda}S(t)$  is uniformly continuous on compact sets in X we see that  $\lim_{t\to d^-} u(t)$  exists with  $\lim_{t\to d^-} u(t) = p \in V \subset D$ . Also,

$$|u'(t_2) - u'(t_1)|$$

$$\leq |T(t_{2})GS(t_{2})x - T(t_{1})GS(t_{1})x| + |T(t_{2})BC(t_{2})x - T(t_{1})BC(t_{1})x|$$

$$+ |T(t_{2})C(t_{2})(Bx + y) - T(t_{1})C(t_{1})(Bx + y)|$$

$$+ |T(t_{2})BS(t_{2})(Bx + y) - T(t_{1})BS(t_{1})(Bx + y)|$$

$$+ \int_{t_{1}}^{t_{2}} |T(t_{2} - s)C(t_{2} - s)F(u(s)) - T(t_{2} - s)BS(t_{2} - s)F(u(s))| ds$$

$$+ \int_{0}^{t_{1}} |[T(t_{2} - s)C(t_{2} - s) - T(t_{1} - s)C(t_{1} - s)]F(u(s))| ds$$

$$+ \int_{0}^{t_{1}} |[T(t_{2} - s)BS(t_{2} - s) - T(t_{1} - s)BS(t_{1} - s)]F(u(s))| ds .$$

Again, using the fact that  $\{F(u(s)): 0 \le s < d\}$  is precompact in X and that  $t \to T(t)C(t)$  and  $t \to T(t)BS(t)$  are continuous uniformly on compact sets of X, it follows that  $\lim_{t\to d^-} u'(t) = q \in X$  exists. Noting that

$$p = T(d)[C(d)x + S(d)(Bx + y)] + \int_0^d T(d - s)S(d - s)F(u(s)) ds$$

and

$$q = T(d)[GS(d)x + C(d)(Bx + y)] - BT(d)[C(d)x + S(d)(Bx + y)]$$

$$- \int_0^d BT(d - s)S(d - s)F(u(s)) ds + \int_0^d T(d - s)C(d - s)F(u(s)) ds,$$

we see that  $p \in D \cap D(B)$  and  $q \in X$ . Thus one can obtain a solution of the equation

$$v(t) = T(t-d)[C(t-d)p + S(t-d)(Bp+q) + \int_{d}^{t} T(t-s)S(t-s)F(v(s)) ds$$

for  $d \le t < d^*$ . One then extends u to  $[0,d^*)$  by defining u(t) = v(t) on  $[d,d^*)$ . Using the properties found in Proposition 2.1 (in particular, identities (vii) and (viii)), one can show for  $t \in [d,d^*)$  that

$$u(t) = v(t) = T(t)[C(t)x + S(t)(Bx + y)] + \int_0^t T(t-s) S(t-s)F(u(s)) ds,$$

contradicting the noncontinuability of u.

4. ASYMPTOTIC BEHAVIOR. In this section we will assume T(t) decays exponentially as  $t \to \infty$ ; i.e., there exists b > 0 such that  $|T(t)| \le Me^{-bt}$  for all  $t \in [0,\infty)$ . For convenience, we assume M = 1.

THEOREM 4.1. In addition to the suppositions of Theorem 3.2, suppose  $F \text{ maps bounded sets of } X_{\lambda} \text{ into bounded sets of } X_{\beta}. \text{ Also, suppose} \\ b < \omega_{\lambda}, \ x \in X_{\gamma} \text{ for some } \lambda < \gamma < 1 \text{ with } Bx \in X_{\beta}, \ y \in X_{\beta} \text{ and } u \text{ is a} \\ \text{solution of (1.2) defined and bounded on } [0,\infty). \text{ Then } \{u(t): t \geq 0\} \text{ is} \\ \text{precompact in } X_{\lambda}. \text{ A similar assertion holds under the hypotheses of} \\ \text{Theorem 3.3.}$ 

**Proof.** Choose  $1 > \gamma > 0$  such that  $\lambda < \gamma < \lambda + \beta$ . Then

$$(-G_c)^{\gamma} u(t) = (-G_c)^{\gamma} T(t) [C(t)x + S(t)(Bx + y)]$$

$$+ (-G_c)^{\gamma} \int_0^t T(t - s)S(t - s)F(u(s)) ds$$

$$= T(t)C(t)(-G_c)^{\gamma} x + T(t)(-G_c)^{\lambda} S(t)[(-G_c)^{\gamma - \lambda}(Bx + y)]$$

$$+ \int_0^t T(t - s)(-G_c)^{\lambda} S(t - s)(-G_c)^{\gamma - \lambda} F(u(s)) ds$$

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and thus

$$\begin{aligned} \left| \left( -G_{c} \right)^{\gamma} u(t) \right| & \leq Ke^{\left( -b + \omega \right) t} \left| x \right|_{\gamma} + M_{\lambda} e^{\left( -b + \omega_{\lambda} \right) t} \left| Bx + y \right|_{\gamma - \lambda} \\ & + M_{\lambda} \int_{0}^{t} e^{\left( -b + \omega_{\lambda} \right) (t - s)} \left| F(u(s)) \right|_{\gamma - \lambda} ds. \end{aligned}$$

Consequently,  $\{(-G_c)^{\gamma}u(t) \mid \text{ is bounded and } \{(-G_c)^{\lambda}u(t): t \ge 0\} = \{(-G_c)^{\lambda-\gamma}(-G_c)^{\gamma}u(t): t \ge 0\}$  is precompact in X.

THEOREM 4.2. In addition to the hypotheses of Theorem 3.4 with D = X , suppose there exists a continuous function  $j\colon\mathbb{R}^+\to\mathbb{R}^+$  with j(0)=0 such that  $\big|F(x)\big|_{\beta}\leq j(r)\big|x\big|_{\lambda}$  for  $x\in X_{\lambda}$  and  $\big|x\big|_{\lambda}\leq r$ . If  $x\in X_{\lambda}\cap D(B)$  and  $y\in X$ , then there exists  $\varepsilon>0$ ,  $N\geq 1$ , and  $\delta>0$  such that if  $\big|x\big|_{\lambda}\leq \varepsilon/2$  and  $\big|y\big|\leq \varepsilon/2$  then the solution of (1.2) exists on  $[0,\infty)$  and satisfies  $\big|u(t)\big|_{\lambda}\leq Ne^{-\delta t}(\big|x\big|_{\lambda}+\big|Bx+y\big|)$ .

Proof. Let  $N = \max\{K, M_{\lambda}\}$ ,  $\epsilon_1 > 0$  such that  $j(\epsilon_1) < (b - \omega_{\lambda})/2$ , and  $\epsilon = \epsilon_1/N$ . For  $|x|_{\lambda} \le \epsilon/2$  and  $|y| \le \epsilon/2$ , let u be the solution of equation (1.2) and  $[0,t^*]$  ( $[0,\infty)$  if  $t^* = \infty$ ) the maximal interval such that  $|u(t)|_{\lambda} \le \epsilon_1$  for all  $0 \le t < t^*$ . For  $0 \le t < t^*$ ,

$$(-G_c)^{\lambda} u(t)$$
=  $T(t)[C(t)(-G_c)^{\lambda}x + (-G_c)^{\lambda}S(t)(Bx + y)] + \int_0^t T(t-s)(-G_c)^{\lambda}S(t-s)F(u(s)) ds$ 

and

$$\begin{aligned} &\left|u(t)\right|_{\lambda} \\ &\leq e^{-bt} \left[ Ke^{\omega t} \left|x\right|_{\lambda} + M_{\lambda} e^{\omega_{\lambda} t} \left|Bx + y\right| \right] + \left( \frac{b - \omega_{\lambda}}{2} \right) M_{\lambda} \int_{0}^{t} e^{-b(t-s)} e^{\omega_{\lambda} (t-s)} \left|u(s)\right|_{\lambda} ds. \end{aligned}$$

Thus

$$e^{(b-\omega_{\lambda})t}|u(t)|_{\lambda}$$

$$\leq K|x|_{\lambda} + M_{\lambda}|Bx + y| + \frac{b-\omega_{\lambda}}{2} M_{\lambda} \int_{0}^{t} e^{(b-\omega_{\lambda})s} |u(s)|_{\lambda} ds$$

and Gronwall's inequality yields

$$|u(t)|_{\lambda} \le N(|x|_{\lambda} + |Bx + y|)e^{[(b-\omega_{\lambda})/2](Nt)}$$

Thus  $\delta = [(b - \omega_{\lambda})/2]N$  and  $t^* = \infty$  by Theorem 3.4.

5. EXAMPLES. We first consider the equation

(5.1) 
$$w_{tt}(x,t) + 2b(x)w(x,t) = w_{xx}(x,t) + f(w(x,t)), \quad 0 < x < \pi, \ t \in \mathbb{R}$$

$$w(0,t) = w(\pi,t) = 0, \quad t \in \mathbb{R}$$

$$w(x,0) = h(x), \quad w_{t}(x,0) = g(x), \quad 0 \le x \le \pi$$

where h and g are in  $\mathcal{L}_2(0,\pi;\mathbb{R})$  and b:  $[0,\pi] \to \mathbb{R}$  is continuous. Let  $X = \mathcal{L}_2(0,\pi;\mathbb{R})$  with inner product ( , ) and define A:  $D(A) \to X$  by  $A\phi = \phi''$  where

D(A) = 
$$\{\phi \in X: \phi, \phi' \text{ are absolutely continuous,}$$
  
 $\phi'' \in X, \phi(0) = \phi(\pi) = 0\}.$ 

A can be written in the form

$$A\phi = -\sum_{n=1}^{\infty} n^2(\phi, \phi_n)\phi_n$$

for  $\phi \in D(A)$ , where  $\phi_n(x) = (2/\pi)^{1/2} \sin(nx)$ . We define B:  $X \to X$  by  $[B\phi]x = b(x)\phi(x)$ . Defining  $G = A + B^2$  we have

$$[G\phi]x = \sum_{n=1}^{\infty} (-n^2 + b(x)) (\phi, \phi_n) \phi_n(x)$$

and G generates the cosine family

$$[C(t)\phi](x) = \sum_{n=1}^{\infty} C_n(x,t)(\phi,\phi_n)\phi_n(x)$$

where

$$C_{n}(x,t) = \begin{cases} \cos(n^{2} - b^{2}(x))^{1/2}t, & n^{2} > b^{2}(x) \\ 1, & n^{2} = b^{2}(x) \\ \cosh(b^{2}(x) - n^{2})^{1/2}t, & n^{2} < b^{2}(x). \end{cases}$$

Also,

$$[S(t)f](x) = \sum_{n=1}^{\infty} s_n(x,t)(\phi,\phi_n)\phi_n(x)$$

where

$$s_{n}(x,t) = \begin{cases} (n^{2} - b^{2}(x))^{-1/2} \sin(n^{2} - b^{2}(x))^{1/2}t &, n^{2} > b^{2}(x) \\ t &, n^{2} = b^{2}(x) \\ (b^{2}(x) - n^{2})^{-1/2} \sinh(b^{2}(x) - n^{2})^{1/2}t &, n^{2} < b^{2}(x). \end{cases}$$

Note also that -B generates the group  $\{T(t): t \in \mathbb{R}\}$  on X defined by  $[T(t)\phi]x = e^{-tb(x)}\phi(x)$  and D(B) = X. It is easily seen that properties (2.1) - (2.7) are satisfied. Property (2.8) is established by the following proposition.

PROPOSITION 5.1. Let A, B, C(t), S(t), T(t) be as above. Then (2.8) is satisfied, i.e., for  $\phi \in X$ ,  $f_{\mathbf{r}}^{\mathbf{S}} T(\mathbf{u}) S(\mathbf{u}) \phi$  du  $\in D(A)$  and

$$\Lambda \int_{\mathbf{r}}^{S} T(u)S(u)\phi \ du = T(s)C(s)\phi - T(\mathbf{r})C(\mathbf{r})\phi + BT(s)S(s)\phi - BT(\mathbf{r})S(\mathbf{r})\phi.$$

**Proof.** Using the fact that C(t)T(s) = T(s)C(t) for all  $t,s \in \mathbb{R}$  and identity (viii) in Proposition (2.1), we have

$$j(t) \stackrel{\text{def}}{=} C(t) \int_{\mathbf{r}}^{\mathbf{S}} T(u)S(u)\phi \ du = \frac{1}{2} \int_{\mathbf{r}}^{\mathbf{S}} T(u) \left(S(u+t) + S(u-t)\right)\phi \ du.$$

Thus

$$j'(t) = \frac{1}{2} \int_{\mathbf{r}}^{\mathbf{s}} T(u) (C(u + t) - C(u - t)) \phi du$$

$$= \frac{1}{2} \int_{\mathbf{r}+t}^{\mathbf{s}+t} T(u - t) C(u) \phi du - \frac{1}{2} \int_{\mathbf{r}-t}^{\mathbf{s}-t} T(u + t) C(u) \phi du$$

and

$$J''(t) = \frac{1}{2} \left[ T(s)C(s+t)\phi - T(r)C(r)\phi \right] + \frac{1}{2} \int_{r+t}^{s+t} BT(u-t)C(u)\phi \ du$$

$$+ \frac{1}{2} \left[ T(s)C(s-t)\phi - T(r)C(r-t)\phi \right] + \frac{1}{2} \int_{r-t}^{s-t} BT(u+t)C(u)\phi \ du.$$

Integrating by parts,

$$(A + B^{2}) \int_{\mathbf{r}}^{\mathbf{S}} T(u)S(u)\phi du = C^{**}(0) \int_{\mathbf{r}}^{\mathbf{S}} T(u)S(u)\phi du$$

$$= T(s)C(s)\phi - T(r)C(r)\phi + \int_{\mathbf{r}}^{\mathbf{S}} BT(u)C(u)\phi du$$

$$= T(s)C(s)\phi - T(r)C(r)\phi + BT(s)S(s)\phi - BT(r)S(r)\phi$$

$$+ \int_{\mathbf{r}}^{\mathbf{S}} B^{2}T(u)C(u)\phi du$$

from which (2.8) follows.

As noted in the comments preceding condition (3.1), condition (3.1) is satisfied with  $\lambda = 1/2$ . Also, if c is such that  $b^2(x) - c^2 \le 0$ 

for all  $x \in [0,\pi]$ , we see that  $G_c^{-1}$  exists, satisfies

$$[G_c^{-1}\phi](x) = \sum_{n=1}^{\infty} (-n^2 + b^2(x) - c^2)^{-1}(\phi,\phi_n)\phi_n(x),$$

and is compact. Furthermore,

$$[(-G_c)^{1/2}\phi]x = \sum_{n=1}^{\infty} (n^2 - b^2(x) + c^2)^{1/2}(\phi,\phi_n)\phi_n(x).$$

Since

$$D((-G_c)^{1/2}) = \{ \phi \in X : \sum_{n=1}^{\infty} (n^2 - b(x) + c^2) (\phi, \phi_n)^2 < \infty \}$$

$$= \{ \phi \in X : \sum_{n=1}^{\infty} n^2 (\phi, \phi_n)^2 < \infty \},$$

we have from Travis and Webb [7] that

$$D((-G_c)^{1/2}) = \{\phi \in X: \phi \text{ is absolutely continuous,} \\ \phi' \in X, \text{ and } \phi(0) = \phi(\pi) = 0\}.$$

Noting that for  $\phi \in D((-G_c)^{1/2})$ 

$$|\phi'| = \int_0^{\pi} \left[ \sum_{n=1}^{\infty} (\phi', \phi_n) \phi_n(x) \right]^2 dx$$

$$= \int_0^{\pi} \left[ \sum_{n=1}^{\infty} n \left( \frac{2}{\pi} \right)^{1/2} (\phi, \phi_n) \cos(nx) \right]^2 dx$$

$$= \sum_{n=1}^{\infty} n^2 (\phi, \phi_n)^2$$

and

$$|\phi|_{1/2} = |-G_c^{1/2}\phi|$$

$$= \int_0^{\pi} \left[ \sum_{n=1}^{\infty} (n^2 - b^2(x) + c^2)^{1/2} (\phi, \phi_n) \phi_n(x) \right]^2 dx$$

$$= \sum_{n=1}^{\infty} (n^2 - b^2(x) + c^2) (\phi, \phi_n)^2$$

it follows that there exists K > 0 such that for all  $\phi \in D((-G_c)^{1/2})$ 

$$\kappa |\phi'| \ge |\phi|_{1/2} \ge |\phi'|$$
.

If  $f(w) = -aw - bw^3$ , a,b > 0 or  $f(w) = \sin w$  then equation (5.1) is the Klein-Gordon or Sine-Gordon equation respectively and  $[F(\phi)]x = f(\phi(x))$  satisfies the conditions of Theorem 3.2 with  $F: X_{1/2} \to X_{1/2}$ . For example, to see  $F: X_{1/2} \to X_{1/2}$  defined by  $[F(\phi)]x = -a\phi(x) - b\phi^3(x)$  is continuous, observe for  $\phi, \psi \in X_{1/2}$ 

$$| F\phi - F\psi |_{1/2} \le K | [F\phi]' - [F\psi]' |$$

$$\le K | a(\phi' - \psi') + 3b(\psi^2 \psi' - \phi^2 \phi') |$$

$$\le aK | \phi' - \psi' | + 3bK (| \psi^2 \psi' - \psi^2 \phi' | + | \phi' (\psi^2 - \phi^2) |)$$

Supp Suppose  $b(x) \ge 0$  for all  $x \in [0,\pi]$  and let  $b_m = \min\{b(x): 0 \le x \le \pi\}$  and  $b_M = \max\{b(x): 0 \le x \le \pi\}$ . Then  $|T(t)| \le e^{-b_M t}$  and there exists  $M_{1/2} > 0$  such that  $|(-G_c)^{1/2}S(t)| \le M_{1/2}e^{W_{1/2}t}$  where  $w_{1/2} = 0$  if  $b_M \le 1$  and  $w_{1/2} = (b_M^2 - 1)^{1/2}$  if  $b_M > 1$ . Consequently, the results of section 4 apply provided  $0 < b_M < b_M \le 1$  or  $b_M > 1$  and  $b_M > (b_M^2 - 1)^{1/2}$ .

As another example, consider

(5.2) 
$$w_{tt}(x,t) + 2w_{xt}(x,t) = w_{xx}(x,t) + f(w(x,t)), \quad 0 < x < \pi, \ t \in \mathbb{R}$$

$$w(x,0) = h(x), \quad w_{t}(x,0) = g(x), \quad 0 \le x \le \pi$$

$$w(0,t) = w(\pi,t), \quad w_{x}(0,t) = w_{x}(\pi,t), \quad t \in \mathbb{R}$$

where h,g  $\in$   $\mathcal{L}_2(0,\pi;\mathbb{R})$ . Again let  $X = \mathcal{L}_2(0,\pi;\mathbb{R})$  with inner product (,) and define A: D(A)  $\rightarrow$  X by A $\phi = \phi''$  where

$$D(A) = \{ \phi \in X : \phi, \phi' \text{ are absolutely continuous,}$$
 
$$\phi'' \in X, \phi(0) = \phi(\pi), \phi'(0) = \phi'(\pi) \}.$$

A can be written in the form

$$A\phi = \sum_{n=1}^{\infty} -4n^2 [(\phi, \phi_n)\phi_n + (\phi, \psi_n)\psi_n]$$

where  $\phi_n(x) = (2/\pi)^{1/2} \sin(2nx)$ ,  $\psi_n(x) = (2/\pi)^{1/2} \cos(2nx)$ , and  $\phi = a + \sum_{n=1}^{\infty} (\phi, \phi_n) \phi_n + (\phi, \psi_n) \psi_n$ ,  $a = (1/\pi) \int_0^{\pi} \phi(x) dx$ . We define B:  $D(B) \to X$  by  $B\phi = \phi'$  where

$$D(B) = \{ \phi \in X : \phi' \in X, \phi(0) = \phi(\pi) \}.$$

The group  $\{T(t): t \in \mathbb{R}\}$  generated by -B is defined by

$$[T(t)\phi]x = a + \sum_{n=1}^{\infty} (\phi,\phi_n)\phi_n(x - t) + (\phi,\psi_n)\psi_n(x - t)$$

and  $G = A + B^2 = 2A$  generates the cosine family

$$[C(t)\phi]x = a + \sum_{n=1}^{\infty} \cos(2\sqrt{2} nt)[(\phi,\phi_n)\phi_n(x) + (\phi,\psi_n)\psi_n(x)].$$

Conditions (2.1) - (2.7) are satisfied and condition (2.8) is verified in the manner indicated by the proof of Proposition 5.1. Also,  $G^{-1}$  exists as a compact operator on X and  $(-G_c)^{1/2}$  exists with

$$(-G_c)^{1/2}\phi = \sum_{n=1}^{\infty} 2\sqrt{2} n[(\phi,\phi_n)\phi_n + (\phi,\psi_n)\psi_n].$$

The existence results of section 3 apply to example (5.2); however, note that since T(t) is of type b = 0 and C(t) is of type w = 0, the asymptotic results of section 4 do not apply.

The abstract theory also applies to the equation

(5.3) 
$$w_{tt} + 2b(x)w_{t} = -w_{xxxx} + f(w,w_{x}), \quad 0 < x < \pi, \quad t \in \mathbb{R}$$

$$w(0,t) = w(\pi,t) = w_{xx}(0,t) = w_{xx}(\pi,t) = 0, \quad t \in \mathbb{R}$$

$$w(x,0) = g(x), \quad w_{+}(x,0) = h(x), \quad 0 \le x \le \pi.$$

As before let  $X = \mathcal{L}_2(0,\pi;\mathbb{R})$ ,  $A\phi = -\phi'''$  with

$$D(A) = \{ \phi \in X : \phi, \phi', \phi'', \phi''' \text{ are absolutely continuous,}$$
 
$$\phi'''' \in X, \phi(0) = \phi(\pi) = \phi''(0) = \phi''(\pi) = 0 \}.$$

In this case,  $[F\phi]x = f(\phi(x), \phi'(x))$  with appropriate conditions on f satisfies  $F: X_{1/4} \to X$  continuous and consequently Theorem 3.3 applies.

REMARK. The techniques also apply to

(5.4) 
$$w_{tt} - 2w_{xxt} = -w_{xxxx} + f(w, w_x), \quad 0 < x < \pi, \quad t \ge 0$$

with the side conditions of (5.3). Here  $B\phi$ :  $-\phi''$  with

$$D(B) = \{ \phi \in X : \phi, \phi' \text{ are absolutely continuous,}$$
 
$$\phi'' \in X, \ \phi(0) = \phi(\pi) = 0 \}.$$

Thus -B generates an analytic semigroup. Since  $A + B^2 = 0$ , C(t)x = x, S(t)x = tx, and equation (1.2) has the form

$$u(t) = T(t)[x + t(Bx + y)] + \int_{0}^{t} (t - s)T(t - s)F(u(s)) ds.$$

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Consider the abstract differential equation		
•		
(1) $u''(t) + 2Bu'(t) = Au(t) + F(u(t)), t \in \mathbb{R}, u(0) = x$		
1		
	$\mathbf{u'}(0) = \mathbf{y}$	
	u'(0) = y continued	

## 20. Abstract (continued)

where A and B are densely defined linear operators and F is possibly nonlinear and unbounded. Assuming that  $A + B^2$  generates a cosine family C(t) and -B generates a group T(t), there is a variation of constants formula for (1); namely

(2) 
$$u(t) = T(t)[C(t)x + S(t)(Bx + y)$$

+ 
$$\int_0^t T(t-s)S(t-s)F(u(s)) ds$$
,

where S(t) is the sine family associated with C(t). The motivating examples include  $w_{tt} + 2b(x)w_t = w_{xx} + f(w,w_x,w_t)$  and  $w_{tt} + 2w_{tx} = w_{xx} + f(w,w_x,w_t)$ , for  $0 < x < \pi$ ,  $t \in \mathbb{R}$ , w(x,0) = h(x),  $w_t(x,0) = g(x)$ , and various boundary conditions. We examine the existence of mild solutions and the asymptotic behavior when there is a damping effect introduced by the  $2Bu^*(t)$  term,

